



## A: Paul Trap

A-1. Due to the symmetry, on the z-axis the only non-zero component of electric field is in the z-direction. So:

$$
\vec{E}(0,0,z) = E_z(0,0,z) \,\hat{z} = \hat{z} \int \frac{dq}{4\pi\epsilon_0} \frac{1}{(R^2 + z^2)} \times \frac{z}{(R^2 + z^2)^{\frac{1}{2}}}
$$

The element  $dq$  is equal to  $\lambda R d\phi$  where  $\phi$  is the angle with the x-axis. Thus:

$$
E(0,0,z) = \hat{z} \int \frac{\lambda R d\phi}{4\pi \epsilon_0} \frac{z}{(z^2 + R^2)^{\frac{3}{2}}} = \hat{z} \frac{\lambda R}{2\epsilon_0} \frac{z}{(z^2 + R^2)^{\frac{3}{2}}}
$$

For  $z \ll R$  this can be written as:

$$
E_z(0,0,z) = \frac{\lambda R}{2\epsilon_0} \frac{z}{R^3} = \frac{\lambda z}{2\epsilon_0 R^2}
$$

Very close to the z-axis, we can write:

$$
E_z(x, y, z) = E_z(0, 0, z) + x \frac{\partial E_z}{\partial x}\big|_{(0, 0, z)} + y \frac{\partial E_z}{\partial y}\big|_{(0, 0, z)} + O(x^2, y^2, z^2)
$$

Since, there is no difference between x and  $-x$  or y and  $-y$ , it turns out that  $\frac{\partial E_z}{\partial x} = \frac{\partial E_z}{\partial y} = 0$ . Thus, to the first order in  $x$ ,  $y$ , and  $z$  we have:

$$
E_z(x, y, z) = \frac{\lambda z}{2\epsilon_0 R^2}
$$

Consider a Gaussian surface in the shape of a symmetric cylinder around the z-axis whose bases are parallel with the xy-plane. The cylinder's radius is  $\rho$  and its height is 2z both of which are small quantities. By Gauss's law we have:







$$
0 = \frac{Q_{in}}{\epsilon_0} = \oint \vec{E} \cdot d\vec{S} = \int_{S_1} \vec{E} \cdot d\vec{S} + \int_{S_2} \vec{E} \cdot d\vec{S} + \int_{S_3} \vec{E} \cdot d\vec{S}
$$

Integration over  $S_1$  and  $S_2$  gives:

$$
\int_{S_1} \vec{E} \cdot d\vec{S} = \int_{S_2} \vec{E} \cdot d\vec{S} = \pi \rho^2 \times \frac{\lambda z}{2\epsilon_0 R^2}.
$$

Integration over  $S_3$  involves the  $\rho$ -component for which we can write the following expansion:

$$
E_{\rho}(z,\rho,\phi) = E_{\rho}(0,\rho,\phi) + z \frac{\partial E_{\rho}}{\partial z}|_{(0,\rho,\phi)} + O(z^2)
$$

We have  $0 = \frac{\partial E_{\rho}}{\partial z}$  $\frac{\partial L_{\rho}}{\partial z}|_{(0,\rho,\phi)}$  due to symmetry between z and  $-z$ , hence,  $E_{\rho}(z,\rho,\phi) = E_{\rho}(0,\rho,\phi)$ up to the first order. Axial symmetry also implies  $\frac{dE_{\rho}}{d\phi} = 0$ . Consequently:

$$
\int_{S_3} \vec{E} \cdot d\vec{S} = E_{\rho}(0, \rho, 0) \times 2z \times 2\pi\rho
$$

So, Gauss's law implies:

$$
0 = E_{\rho} \times 4\pi z \rho + 2\pi \rho^2 \frac{\lambda z}{2\epsilon_0 R^2}
$$

Therefore,  $E_{\rho}$  will be:

$$
E_{\rho} = -\frac{\lambda \rho}{4\epsilon_0 R^2}
$$

In the cylindrical coordinate we will have:

$$
\vec{E}(\rho,\phi,z)=-\frac{\lambda\rho}{4\epsilon_0R^2}\hat{\rho}+\frac{\lambda z}{2\epsilon_0R^2}\hat{z}
$$

In cartesian coordinates we will have:

$$
\vec{E}(x, y, z) = \frac{\lambda}{4\epsilon_0 R^2}(-x, -y, 2z)
$$

Since the ring is positively charged, the equilibrium in the  $x$  and  $y$  directions are stable, while the equilibrium in the z-direction is unstable. The equations of motion in the  $x$  and  $y$  directions read:

$$
m\ddot{x} = qE_x = -\frac{q\lambda}{4\epsilon_0 R^2}x
$$

$$
m\ddot{y} = qE_y = -\frac{q\lambda}{4\epsilon_0 R^2}y
$$





Therefore, the frequencies of small oscillations are:

$$
\omega_x^2 = \omega_y^2 = \frac{q\lambda}{4\epsilon_0 R^2 m}
$$

A-1 (1.5 pt)  
\n(a) 
$$
\vec{E}(x, y, z) = \frac{-\lambda x}{4\epsilon_0 R^2} \hat{x} + \frac{-\lambda y}{4\epsilon_0 R^2} \hat{y} + \frac{\lambda z}{2\epsilon_0 R^2} \hat{z}
$$
  
\n(b)  $\omega_x = \omega_y = \sqrt{\frac{Q\lambda}{4\epsilon_0 R^2 m}}$ 

## A-2.

The force in the z-direction is:

$$
F_z = qE_z = \frac{Q\lambda z}{2\epsilon_0 R^2} = \frac{Q}{2\epsilon_0 R^2} \lambda_0 z + \frac{Qu}{2\epsilon_0 R^2} \cos \Omega t z
$$

the equation of motion can thus be written as:

$$
\ddot{z} = \left(\frac{Q\lambda_0}{2\epsilon_0 R^2 m} + \frac{Qu}{2\epsilon_0 R^2 m} \cos \Omega t\right) z
$$

Therefore:

$$
k = \sqrt{\frac{Q\lambda_0}{2\epsilon_0 R^2 m}}
$$
 , 
$$
a = \frac{Qu}{2\epsilon_0 R^2 m \Omega^2}
$$

A-2 (0.4 pt)  $k =$  $Q\lambda_0$  $2\epsilon_0R^2m$ 

$$
, a = \frac{Qu}{2\epsilon_0 R^2 m \Omega^2}
$$

A.3.

$$
z = p(t) + q(t) \qquad \rightarrow \qquad \ddot{p} + \ddot{q} = (k^2 + a\Omega^2 \cos \Omega t)(p + q)
$$

- 1. We are assuming that  $p$  is almost constant,  $\ddot{p} \simeq 0$ .
- 2. According to the assumptions  $k^2 \ll a\Omega^2$  and  $q \ll p$  we can ignore  $k^2$  in the first term on the right-hand side of the equation and  $q$  in the second term.

hence, the equation of motion can be simplified as follows:

$$
\ddot{q} = pa\Omega^2 \cos \Omega t.
$$





As we have assumed that  $p$  is a constant, the second derivative of  $q$  is just proportional to cos  $Ωt$  which gives:

 $1.1.1.1.1.1.$ 

$$
q = -pa\cos\Omega t + c_1t + c_2.
$$

Since q is supposed to remain small,  $c_1$  must vanish. Also  $c_2 = 0$  because the mean value of *q* is supposed to remain zero. Therefore:

 $q = -pa \cos \Omega t$ 

A-3 (1.8 pt) (a)  $\ddot{q}(t) = pa\Omega^2 \cos \Omega t$ (b)  $q(t) = -pa \cos \Omega t$ 

A-4. Using the final result for  $q$  the equation of motion for  $p$  reads:

$$
\ddot{p} + pa\Omega^2 \cos \Omega t = (k^2 + a\Omega^2 \cos \Omega t)(p - ap\cos \Omega t)
$$

Which gives:

$$
\ddot{p} = k^2 p - ak^2 p \cos \Omega t - a^2 \Omega^2 p \cos^2 \Omega t
$$

Averaging over one period, we'll have:

$$
\langle \cos \Omega t \rangle = 0 \qquad , \qquad \langle \cos^2 \Omega t \rangle = \frac{1}{2}
$$

and:

$$
\ddot{p} = \left(k^2 - \frac{a^2 \Omega^2}{2}\right)p.
$$

In order for the motion to be stable, the expression inside the parentheses should be negative, i.e.

$$
\frac{a^2\Omega^2}{2} > k^2 \qquad \rightarrow \qquad \Omega > \sqrt{2}\frac{k}{a}
$$

A-4 (1.5 pt)  
\n(a) 
$$
\ddot{p}(t) = \left(k^2 - \frac{a^2 \Omega^2}{2}\right) p
$$
  
\n(b)  $\Omega > \sqrt{2} \frac{k}{a}$ 

A.5. With the given data we have:





$$
k = \sqrt{\frac{Q\lambda_0}{2\epsilon_0 R^2 m}} = 2 \times 10^5 \text{ rad/s}
$$

. . . . . . . . . . . .

$$
a = 0.04
$$
  $\rightarrow$   $\Omega_{\text{min}} = 7 \times 10^6 \text{ rad/s}$ 

which is in the range of radio waves.

A-5 (0.4 pt)  
\n
$$
k = 2 \times 10^5
$$
 rad/s  
\n $\Omega_{\text{min}} = 7 \times 10^6$  rad/s

## B: Doppler Cooling

B-1. From the uncertainty principle we know:

 $\Delta E \times \Delta t \simeq \hbar$ 

Here  $\Delta t$  is the time  $\tau$  and  $\Delta E = \hbar \Delta \omega$ . So:

$$
\hbar \Delta \omega \times \tau \simeq \hbar \quad \rightarrow \quad \Delta \omega \simeq \frac{1}{\tau} = \Gamma
$$



B-2. We denote the forward and backward collision rates by  $s_+$  and  $s_-$  respectively. Let us proceed in the atom's frame of reference. Ignoring the terms of the order  $\frac{v^2}{r^2}$  $\frac{v}{c^2}$ , the Doppler effect can be written in the following form:

$$
\omega' = \omega \left( 1 + \frac{v}{c} \right)
$$

Taking the atom's velocity in the positive  $x$ -direction, we have:





 $\omega_+ = \omega_L (1 +$  $\boldsymbol{\mathcal{V}}$  $\mathcal{C}_{0}$ )  $\omega_-=\omega_{\rm L} (1-\$  $\mathcal{V}$  $\mathcal{C}_{0}^{0}$ )

So:

$$
s_{+} = s_{L} + \alpha \left(\omega_{L} \left(1 + \frac{v}{c}\right) - \omega_{L}\right) = s_{L} + \alpha \omega_{L} \frac{v}{c}
$$

$$
s_{-} = s_{L} + \alpha \left(\omega_{L} \left(1 - \frac{v}{c}\right) - \omega_{L}\right) = s_{L} - \alpha \omega_{L} \frac{v}{c}
$$

The momentum transfer per unit time from the oncoming photons to the atom is equal to:

$$
\pi_+ = s_+ \times (-\hbar k_+)
$$

For the backward photons we have:

$$
\pi_{-}=s_{-}\times(+\hbar k_{-})
$$

Where  $k_{\pm} = \frac{\hbar \omega_{\pm}}{c}$  $\frac{\omega_{\pm}}{c}$ .

The total momentum transferred to the atom per unit time is equal to:

$$
\pi_{+} + \pi_{-} = -2\hbar k_{\mathrm{L}} \frac{\nu}{c} \omega_{\mathrm{L}} \alpha \left( 1 + \frac{s_{\mathrm{L}}}{\alpha \omega_{\mathrm{L}}} \right)
$$

Where with the approximation  $s_L \ll \alpha \omega_L$ , we will arrive at:

$$
\pi_{+} + \pi_{-} = -2\hbar k_{\mathrm{L}} \frac{v}{c} \omega_{\mathrm{L}} \alpha
$$

Note that as the atom is heavy, its velocity almost doesn't change after the absorption of the photon. Therefore, there will be almost no Doppler shifting in the re-emitted photon and hence, on average there will be no momentum transfer to the atom during the re-emission process.

The above expression is, in fact, the force. Since  $v > 0$ , we have:

$$
F=-(2\alpha\hbar k_{\rm L}^2)v
$$

The same result holds for  $v < 0$ . This is in the atom's reference frame. However, as we have kept only up to the first order in  $v/c$ , the same result holds in the lab frame:

$$
F = -(2\alpha\hbar k_{\rm L}^2)v
$$

**S2-7 IRP** ysics Olympi Isfahan Iran 2024 B-2 (1.7 pt)  $\mathcal{V}$  $s_+ = s_L + \alpha \omega_L$  $\mathcal{C}_{0}^{0}$  $\boldsymbol{\mathcal{V}}$  $s_{-} = s_{L} - \alpha \omega_{L}$  $\mathcal{C}_{0}^{0}$  $\pi_+ = s_+ \times (-\hbar k_+)$  $\pi_{-} = s_{-} \times (+\hbar k_{-})$  $F = -(2\alpha\hbar k_{\rm L}^2)v$ 

B-3. The atom's momentum before the collision is zero. After the collision it will be (assuming the photon's momentum is in the  $x$ -direction):

$$
P_1 = \hbar k_{\rm L}
$$

After re-emitting the photon, we may have two equally likely outcomes for the final momentum:

- 1. The photon is emitted in the positive  $x$ -direction which causes the atom's momentum to become zero
- 2. The photon is emitted in the negative  $x$ -direction which causes the atom's momentum to become:  $P_f = +2\hbar k_L$

Thus, the mean final energy is equal to:

$$
\langle E_{\rm f} \rangle = \langle \frac{P_{\rm f}^2}{2m} \rangle = \frac{1}{2} \times 0 + \frac{1}{2} \times \frac{4\hbar^2 k_{\rm L}^2}{2m} = \frac{\hbar^2 k_{\rm L}^2}{m}
$$

This process occurs during the time  $\tau$ . So, the input power (the power gained by the atom as a result of this process) is equal to:

$$
P_{\rm in} = \frac{\hbar^2 k_{\rm L}^2}{m\tau}
$$

B-3 (1.0 pt)  $P_{\text{in}} =$  $\hbar^2 k_{\rm L}^2$  $m\tau$ 

B.4. The output power (the power lost by the atom through collision with laser photons) can be written as:





$$
P_{\text{out}} = F \cdot v = -2\alpha \hbar k_{\text{L}}^2 v^2
$$

At equilibrium we should have:

$$
P_{\text{out}} + P_{\text{in}} = 0 \quad \rightarrow \quad \frac{\hbar^2 k_{\text{L}}^2}{m\tau} = 2\alpha\hbar k_{\text{L}}^2 \overline{v^2} \qquad \rightarrow \qquad \overline{v^2} = \frac{\hbar\Gamma}{2\alpha m}
$$

And the temperature of this system is equal to:

$$
\frac{1}{2}m\overline{v^2} = \frac{1}{2}k_BT \qquad \rightarrow \qquad T = \frac{\hbar\Gamma}{2\alpha k_B}
$$

B-4 (0.8 pt)  
\n
$$
P_{\text{out}} = -2\alpha \hbar k_{\text{L}}^2 v^2
$$
\n
$$
\overline{v^2} = \frac{\hbar \Gamma}{2\alpha m}
$$
\n
$$
T = \frac{\hbar \Gamma}{2\alpha k_{\text{B}}}
$$

B-5. Considering the given data:

$$
T = \frac{1.055 \times 10^{-34} \text{ J.s}}{2 \times 4 \times 1.381 \times 10^{-23} \text{ J/K} \times 5 \times 10^{-9} \text{ s}} = 2 \times 10^{-4} \text{ K}
$$

B-5 (0.4 pt)  $T = 2 \times 10^{-4}$  K